

the device having two stable equilibrium positions wherein a first stable equilibrium position comprises a first surface having a concave shape and a second surface having a convex shape and a second stable equilibrium position comprises the second surface having a concave shape and the first surface having a convex shape, whereby manual manipulation of the device inverts the first and second surfaces between the two [stable] stable equilibrium positions

wherein the second equilibrium position provides a shape that is substantially the same as the shape of the device in the first equilibrium position and the device will hold the second equilibrium position until an external force causes it to return to the first equilibrium position.

REMARKS

In the Office Action dated October 6, 2000, claims 1-17 are pending and all claims are rejected. The rejection is made final. Applicant requests reconsideration for at least the reasons discussed herein. The above amendment is submitted to further clarify the present invention.

Applicant appreciates the courteous telephone interview extended by Examiners Cegielnik and Ackun to his attorney on January 9, 2001. During the interview the present invention was discussed and contrasted to the cited references, Bullard and Davis, the substance of which is included in the remarks below. The examiners